





Features:

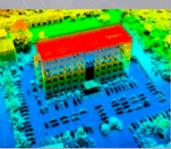
- 8 laser heads with 360° FOV
- MEMS IMU
- Rugged system controller
- Autonomous operation
- 20mp RGB calibrated camera
- One button startup
- 3 returns with intensity
- Fits in small size Pelican® case
- Installation in minutes
 - Area and corridor 3D data acquisition
 - Terrain modeling for precise farming
 - Historical site mapping
 - Other corridor mapping
 - Rapid and accurate distance measuring
 - Stockpiles and volumetric calculations

Nano M8 is a mini LiDAR system specially designed to meet the market needs for smaller size UAV aircrafts

The Nano M8 consists of the Quanergy® M8 scanner, a 20mp RGB calibrated camera, a suitable POS system and a LidarSwiss proprietary control unit.

This 2.0kg LiDAR system is a perfect tool for low altitude small area and corridor mapping. Easy to install and operate features ensure the Nano M8 will generate desirable results with minimal training. Coupled with LidarSwiss Geo-LAS software to process the acquired data, measurable terrain models can be derived in a very short time.





Typical Applications:

- Riverbank and coastal line mapping
- Water resource monitoring
- Quick response mudslide analysis
- Disaster management
- Other 3D data applications

Item:

- Laser class
- Wave length
- Laser beam divergence angle Vert = 0.6 Horz = 4.2
- Scanning range
- Scanning angle
- Pulse rate
- Point density
- Scanning mechanism
- Scanning rate
- Pitch/Roll accuracy
- Heading accuracy
- Recording media
- Storage capacity
- Single scanning swath
- Image dimension
- Effective operating range
- Voltage
- Power consumption
- Dimensions (LxWxH)
- Weight
- Working temperature
- Storage temperature

Specification:

Class 1, eye safe Near infrared

200m (80% reflectivity)

User selectable to 360°

400kHz

Up to 100+pts/m²

Rotating laser head

5.10 or 20Hz

0.025°

0.08°

Win 10 system controller

128GB

Up to 200m

20mp 100m

24V

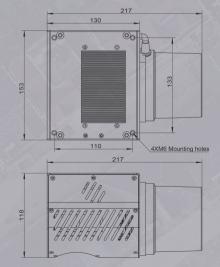
40W (max.)

218mm x 154mm x 119mm

2.0kg

0°C to 40°C

-20°C to 60°C



- Power line inspection/danger tree analysis